

### LMD•M57 programmable Motion Control

#### Product overview

Robust Lexium MDrive® Motion Control products integrate 1.8° 2-phase stepper motors with control electronics. Included are on-board programmable motion controller for stand-alone operation, and optional hMT closed loop performance.

hMT closed loop performance is available in products with either a multi-turn absolute encoder or incremental magnetic encoder. Closed loop performance maintains functional motor control to prevent loss of synchronization, offers variable current control, torque control, and use of the motor's full torque range without derating.

Multi-turn absolute encoders may benefit users by detecting and storing position information, even when powered down. This can eliminate homing routines and reduce setup time at system startup.

Product parameterization, programming and monitoring is through user-friendly software with an RS-422/485 serial interface. Settings can be downloaded and stored in non-volitile memory.

#### Application areas

Especially well suited for industrial applications, products include an IP65 rated version with circular M12 connectors. A high torque motor (LMH•M57) is also available, increasing torque up to 50%.

Compact Lexium MDrive products can reduce machine complexity, size and cost in many stepper and servo motor applications. Their high degree of integration can increase system reliability by reducing the number of individual components, eliminating multiple potential failure points.



LMD•M57 Lexium MDrive Motion Control products: integrated NEMA23 motor and controls, IP65 & IP20-rated

#### Features overview

	NEMACO 400 C. L.			
General	NEMA23 1.8° 2-phase stepper motor integrated with robust control electronics,			
	including programmable motion controller			
	Advanced current control for exceptional performance and smoothness			
Input power	+12 to +60 VDC single supply			
Communication	RS-422/485 serial interface			
	62 software addresses for multi-drop communications			
	Graphical user interface provided for quick and easy parameter setup			
Encoder options	Multi-turn absolute or incremental magnetic			
Motion	20 microstep resolutions up to 51,200 steps per rev including: Degrees, Metric, Arc Minutes			
	336 user program labels / 11,120 bytes flash memory			
	0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments			
I/O, sourcing or sinking	+5 to +24 VDC signal inputs			
	12-bit analog input (1)			
	100ma power outputs			
	5.5mA high-speed signal output			
Protection	Temperature warning			
	IP20, IP65 ratings			
Warranty	4 year, conditional			

(1) Not available on products with multi-turn absolute encoder.



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#### **Specifications**

Communication	Protocol type		RS-422/485		
Input power	Voltage	VDC	+12+60		
		Amp	3.5		
Motor	Frame size	NEMA	23		
		inches	2.3		
		mm	57		
	Performance levels		standard torque or premium high torque		
	Holding torque	oz-in	103 416		
		N-cm	73 294		
	Lenath	stack sizes	1, 2 & 3		
Thermal		Heat sink maximum	85°C		
	non-condensing	Motor maximum	100°C		
Protection	Type	Temperature warning	084°C. user selectable		
	- 7 -	IP rating	IP20, IP65		
		Earth grounding	via product chassis ground lug		
I/O sourcing or sinking	One analog input (2)	Resolution	12 bit		
, o ocaronig or onning	0.10 analog input (2)	Voltage range	0+5 VDC, 0+10 VDC, 020 mA, 420 mA		
Performance levels Holding torque  Length hermal Operating temp non-condensing  Type  O sourcing or sinking  One analog input (2)  Four signal inputs  Two power outputs (3)  One high-speed sign output  ux. logic input Voltage range (4) Incremental magneti  lotion  Microstep resolution  Counters  Velocity  Accel/Decel  oftware  Program storage User registers Floating point registe Math functions  I/O functions  Trip functions  Party-mode address  Party-mode address	Four signal inputs	Voltage range	+5+24 VDC, TTL level compatible		
	r our orginal imputo	Protection	over temp, short circuit, transient, over voltage, inductive clamp		
	Two power outputs (3)	Current rating	-100 +100 mA		
Input power  Motor  Thermal  Protection  I/O sourcing or sinking  Aux. logic input Encoder options  Motion  Software	The ponter outpute (e)	Voltage range	-24+24 VDC		
	One high-speed signal	Current open collector/emitter	5.5 mA		
		Voltage open collector	+60 VDC		
		Voltage open emitter	+7 VDC		
Aux logic input	Voltage range (4)	voltage open emitter	+12 +24 VDC		
		Position update / retention	up to 30 days on internal power; 5 years with optional battery pack		
Ziloodol optiolio		Line count	1000 lines / 4000 edges per rev		
Motion		Number of settings	20		
		Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 arc minute/µstep), 25400 (0.001mm/µstep)		
	Counters	Туре	position, encoder/32 bit		
		Edge rate maximum	5 MHz		
	Velocity	Range	+/- 2,560,000		
Performant Holding to Length Thermal Operating non-conductor Type  // O sourcing or sinking One analogous four signs of the policy of the poli		Resolution	0.5961 steps per second		
	Accel/Decel	Range	1.1 x 10 <sup>9</sup> steps per second <sup>2</sup>		
		Resolution	90.9 steps per second <sup>2</sup>		
		Types	linear, triangle s-curve, sinusoidal s-curve		
Software	Program storage	Type/size	flash / 11,120		
	non-condensing  Type  O sourcing or sinking  One analog input (2)  Four signal inputs  Two power outputs (3)  One high-speed signal output  X. logic input Coder options  Multi-turn absolute Incremental magnetic  Microstep resolution  Counters  Velocity  Accel/Decel  ftware  Program storage User registers Floating point registers Math functions  Branch functions I/O functions	Number/resolution	4 / 32-bit		
		Number/precision	8 / double		
	Math functions	Arithmetic	+, -, X, ÷, >, <, =, >=, <=		
		Logic	AND, OR, XOR, NOT		
		Trigonometric	ABS, COS, ACOS, LOG2, LOG10, PI, SIN, ASIN, SQRT, TAN, ATAN		
	Branch functions		Branch & call		
	I/O functions	Inputs	Home, limit plus, limit minus, go, stop, pause, jog plus, jog minus, general purpose, capture		
		Outputs	Moving, error, velocity change,, moving position, trip, attention. general purpose		
	Trip functions		Trip on input, trip on position, trip on time, trip capture, trip on relative position, trip on main power loss		
	Party-mode addresses		62		
	Encoder functions (5)		stall detection, position maintenance, find index, hMT		

An optional Communication Converter is recommended to facilitate prototyping.

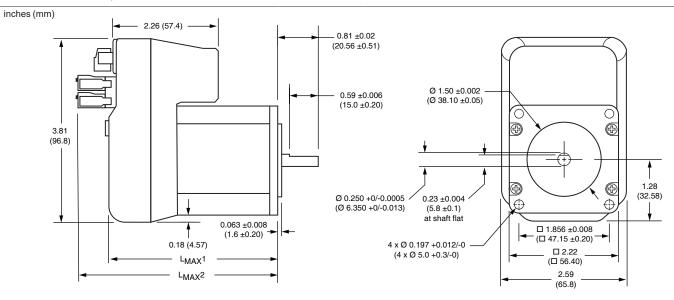


<sup>(1)</sup> Actual power supply current will depend on voltage and load.
(2) Not available on products with multi-turn absolute encoder.
(3) Products with multi-turn absolute encoder have one power output.
(4) When input voltage is removed, maintains power only to control and feedback circuits.
(4) Closed-loop models with encoder only.

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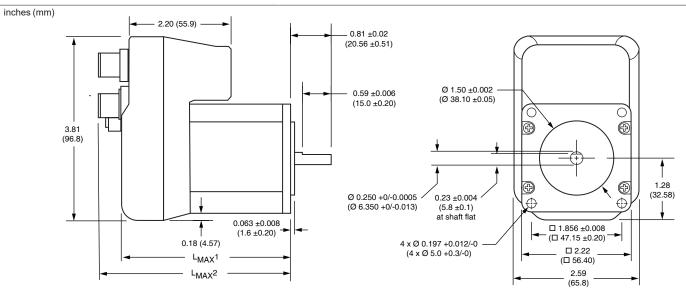
#### **Dimensions**

#### LM•57 NEMA23 motor, IP20-rated



Motor stack length	Lmax1		Lmax2		
	Standard - LMD	High torque - LMH	Standard - LMD	High torque - LMH	
Single	3.17 (80.5)	3.32 (84.3)	3.91 (99.3)	4.01 (101.8)	
Double	3.52 (89.4)	3.73 (94.8)	4.26 (108.2)	4.36 (110.7)	
Triple	4.38 (111.3)	4.60 (116.8)	5.13 (130.3)	5.23 (133.0)	

#### LM•57•C NEMA23 motor, IP65-rated



Stand	dard IMD Iliah			
	uaru - LiviD - High	torque - LMH S	Standard - LMD F	High torque - LMH
Single 3.22 (	(81.8) 3.32	(84.3) 3.	3.91 (99.3)	4.01 (101.8)
Double 3.63 (	(92.3) 3.73	(94.8) 4.	1.26 (108.2)	4.36 (110.7)
Triple 4.50 (	(114.3) 4.60	(116.8) 5.	5.13 (130.3) 5	5.23 (133.0)

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#### LMD•M57 programmable Motion Control

#### IP20-rated products

LEDs

two signal indicators

Chassis ground one #6-32 screw

Connectors

P1: Power 2-pin screw lock

P2: I/O & multifunction 2 keyed 7-pin spring lock

P3: Communication

#### IP65-rated products

LEDs

two signal indicators

Chassis ground one #6-32 screw

Connectors

P1: Power M12 4-pin male

P3: Communication

M12 5-pin female

P2: I/O & multifunction M12 12-pin male



Part numbers

example part number	L M D C M 5 7 1 C
Product LMD = Lexium MDrive with standard hybrid stepper motor LMH = Lexium MDrive with high torque stepper motor	L M D C M 5 7 1 C
Control type C = Closed loop / with hMT and incremental magnetic encoder (1) A = Closed loop / with hMT and multi-turn absolute encoder (1) O = Open loop / no hMT or encoder	L M D C M 5 7 1 C
Communication type M = programmable Motion Control via RS-422/485 serial interface	L M D C M 5 7 1 C
Flange size 57 = NEMA 23 2.3" / 57mm	L M D C M 5 7 1 C
Motor length 1 = single stack 2 = double stack 3 = triple stack	L M D C M 5 7 1 C
Variation — omit from part number if unwanted C = M12 circular connectors and IP65 rating	L M D C M 5 7 1 C

(1) Closed loop control delivers encoder feedback and hMT enhanced motor performance.

#### Accessories

description	length feet (m)	part number
Communication converter USB-pluggable converter to set/program communication parameters in 32- or 64-bit		
Mates to DB9 connector	6.0 (1.8)	MD-CC404-000
Mates to M12 5-pin female connector	6.0 (1.8)	MD-CC405-000
Straight Configuration Cordsets Shielded cables pre-wired with straight M12 mating connectors		
Communication cordset mates to 5-pin female connector	10.0 (3.0)	MD-CS600-000
I/O cordset mates to 12-pin male connector	10.0 (3.0)	MD-CS610-000
Power cordset mates to 4-pin male connector	10.0 (3.0)	MD-CS620-000
Right Angle Configuration Cordsets Shielded cables pre-wired with right angled M12 mating connectors		
I/O cordset mates to 12-pin male connector	10.0 (3.0)	MD-CS611-000
Power cordset mates to 4-pin male connector	10.0 (3.0)	MD-CS621-000
Back-up battery pack for Absolute Encoder models Extend stored position data up to 5-years for 1 to 6 LMDs with absolute encoder		
Battery pack, DIN-rail mount. Uses 3 AA batteries, not provided	_	ICP0531
LMD mating cable(s) with crimp connector to flying lead end	3.3 (1.0)	PD02-0531-FL1
PLC mating cable with crimp connector to flying lead end	3.3 (1.0)	PD04-0531-FL1
Replacement Mating Connector Kit (IP20) Kits for pluggable products		
Includes one 2-pin power mate, and one set (2 pieces) 7-pin multi- function mates		CK-15
Cable Accessory Kit (IP65) Kits for M12 products		

Includes two M12 screw plugs and one sealing cap





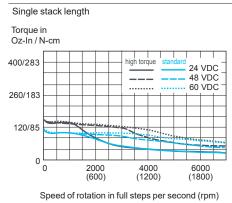
CK-16

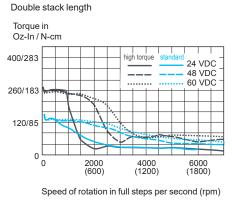
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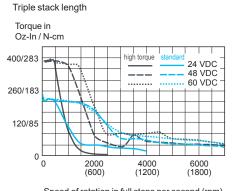
#### Motor performance

LMD•57 standard torque	Motor	Stack length	Single	Double	Triple
NEMA 23 motor specifications		oz-in	103	159	242
	Holding torque	N-cm	73	112	171
		oz-in	3.9	5.6	9.7
	Detent torque	N-cm	2.7	3.9	6.9
	Rotor inertia	oz-in-sec <sup>2</sup>	0.0025	0.0037	0.0065
	Rotor mertia	kg-cm <sup>2</sup>	0.18	0.26	0.46
	Radial load limit, center of shaft	lbs	15	15	15
	Radiai load ilmit, center of shart	kg	6.8	6.8	6.8
	Axial load limit @ 1500rpm	lbs	20	20	20
	(5000 full steps/sec)	kg	9	9	9
	Weight (motor+driver)	OZ	26.4	31.2	44.0
	weight (motor+driver)	g	748	885	1247
LMH•57 high torque NEMA 23 motor specifications	Motor	Stack length	Single	Double	Triple
	11.18	oz-in	152	264	416
	Holding torque	N-cm	107	186	294
	Detent termine	oz-in	8.5	14.2	21.2
	Detent torque	N-cm	6.0	10	15
	Rotor inertia	oz-in-sec <sup>2</sup>	0.0019	0.0030	0.0065
	Rotor mertia	kg-cm <sup>2</sup>	0.14	0.22	0.46
	Radial load limit, center of shaft	lbs	15	15	15
	Radiai load IIIIII, celitei oi silait	kg	6.8	6.8	6.8
	Axial load limit @ 1500rpm	lbs	20	20	20
	(5000 full steps/sec)	kg	9	9	9
	Weight (motor+driver)	OZ	26.4	31.2	44.0
	Weight (motor+driver)	g	748	885	1247

#### LM•57 NEMA 23 speed torque (1)







Speed of rotation in full steps per second (rpm)

(1) Test conditions: 100% current with damper simulating load.

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